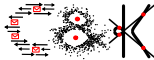
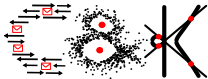


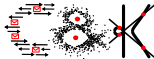
# Constant factor approximation for $k$ -means



$D(\cdot, \cdot)$  squared Euclidean distance



# Constant factor approximation for $k$ -means



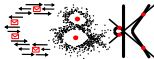
$D(\cdot, \cdot)$  squared Euclidean distance

## Goal

A polynomial time algorithm  $\text{ALG}$  for which there is a constant  $\gamma \geq 1$  such that for every  $P \subset \mathbb{R}^d$ ,  $|P| < \infty$ , and every  $k \in \mathbb{N}$ , algorithm  $\text{ALG}$  on input  $(P, k)$  outputs a set  $C$  of size  $k$  satisfying

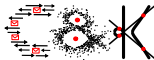
$$D(P, C) \leq \gamma \cdot \text{opt}_k(P).$$

# Constant factor approximation for $k$ -means



$P \subset \mathbb{R}^d$ ,  $D(\cdot, \cdot)$  squared Euclidean distance,  $T \subset \mathbb{R}^d$ ,  $x \in T$

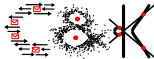
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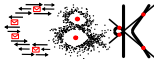
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# Constant factor approximation for $k$ -means



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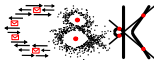
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- $q \in P : t_q := \text{closest point in } T \text{ to } q$
- $K \subseteq \mathbb{R}^d$  called  $(c, k)$ -approximate candidate set, if there is a set  $S \subset K$ ,  $|S| = k$ , with  $D(P, S) \leq c \cdot \text{opt}_k(P)$ , i.e. the best  $k$ -centroid set  $S$  in  $K$  is at most  $c$  times worse than the optimal set of centroids.



## Lemma 5.1

*For all finite sets  $P \subset \mathbb{R}^d$ , and all  $k \in \mathbb{N}$ , the set  $P$  is a  $(2, k)$ -approximate candidate set for itself.*



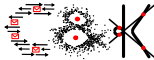
## Lemma 5.1

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## Observation

*If  $K$  is a  $(2, k)$ -approximate candidate set for  $P$  and if  $D(P, S) \leq c \cdot \min_{T \subset K, |T|=k} D(P, T)$ , then  $D(P, S) \leq 2c \cdot \text{opt}_k(P)$ .*





$O := \operatorname{argmin}_{S \subset P, |S|=k} D(P, S)$ , i.e. optimal set of centroids in  $P$ .



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## Definition 5.2

Let  $S \subset P$ .

**1**  $S$  is called *stable*, if for all  $s \in S, s' \in P \setminus S$

$$D(P, S - \{s\} \cup \{s'\}) \geq D(P, S).$$

**2**  $S$  is called  $\epsilon$ -*stable*, if for all  $s \in S, s' \in P \setminus S$

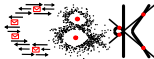
$$D(P, S - \{s\} \cup \{s'\}) \geq (1 - \epsilon)D(P, S).$$



## Observation

*If  $S$  is stable, then for all  $s \in S, o \in O$*

$$D(P, S - \{s\} \cup \{o\}) \geq D(P, S).$$



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$k$ -means-LI( $P$ )

---

choose a set  $S \subset P$  of  $k$  initial centroids;

**repeat**

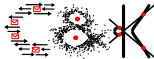
    find  $s \in S, s' \in P \setminus S$  with

$D(P, S - \{s\} \cup \{s'\}) < D(P, S);$

    set  $S := S - \{s\} \cup \{s'\};$

**until**  $S$  is stable;

---



---

$k$ -means-LI( $P$ )

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    set  $S := S - \{s\} \cup \{s'\}$ ;

**until**  $S$  is  $\epsilon$ -stable;

---



## Theorem 5.3

- If  $S$  is a stable set, then

$$D(P, S) \leq 81 \cdot D(P, O).$$

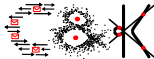
- If  $S$  is a  $\epsilon$ -stable set, then

$$D(P, S) \leq \left(\frac{9}{1-\epsilon}\right)^2 \cdot D(P, O).$$

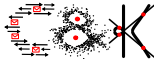
## Corollary 5.4

For any  $\epsilon > 0$ , the  $k$ -means problem can be approximated with factor  $162 + \epsilon$  in time polynomial in the input size and in  $1/\epsilon$ .

# Capturing points



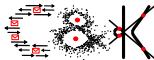
$O \subset P, |O| = k$  optimal set of centroids in  $P$ ,  $S$  stable set,  $|S| = k$ , called set of heuristic centroids.



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- If  $s \in S$  is closest point in  $S$  to  $o \in O$ , then  $s$  captures  $o$ ,  $o$  is captured by  $s$ , and we write  $s = s_o$ .
- If  $s \in S$  captures no element of  $O$ , then  $s$  is called lonely.





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## Partitioning centroids

Partition  $S$  into  $S_1, \dots, S_m$  and  $O$  into  $O_1, \dots, O_m$  such that

- $|S_i| = |O_i|, i = 1, \dots, m$
- if  $s \in S_i$ , then either  $s$  is lonely or  $s$  captures all  $o \in O_i$ .



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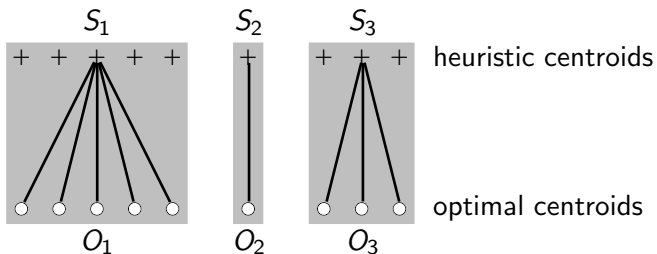
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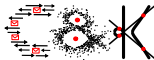


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## Swap pairs

$(s_1, o_1), \dots, (s_k, o_k)$  are called swap pairs, if

- $\forall j : (s_j, o_j) \in \bigcup S_i \times O_i$
- each  $o \in O$  is contained in exactly one pair,
- each  $s$  is contained in at most two pairs,
- for each pair  $(s_j, o_j)$  the element  $s_j$  captures no  $o' \neq o_j$ .



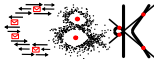
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## Observation

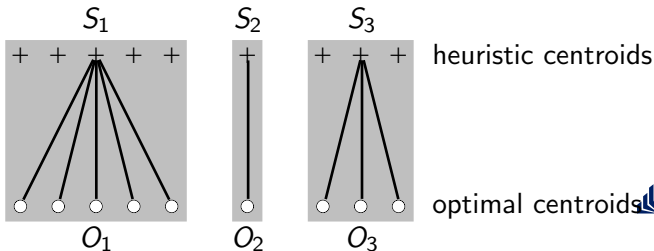
*For each partitioning of centroids  $S_1, \dots, S_m$  and  $O_1, \dots, O_m$  there is a set of swap pairs.*

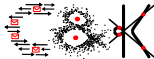


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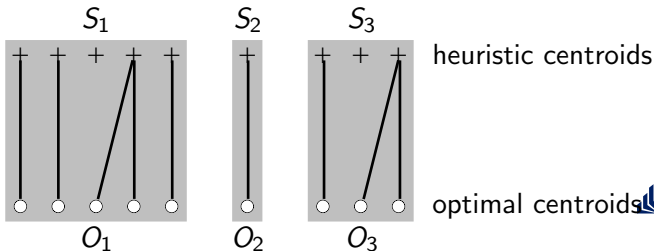




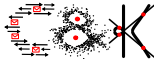
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# Reassignments



Let  $(s, o)$  be a swap pair in set  $\{(s_1, o_1), \dots, (s_k, o_k)\}$  and let  $C_1, \dots, C_k$  be the clusters for set  $S = \{s_1, \dots, s_k\}$ .



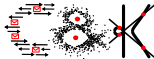


Let  $(s, o)$  be a swap pair in set  $\{(s_1, o_1), \dots, (s_k, o_k)\}$  and let  $C_1, \dots, C_k$  be the clusters for set  $S = \{s_1, \dots, s_k\}$ .

## Reassigning points

For  $S' = S - \{s\} \cup \{o\}$  we define a new clustering of  $P$  as follows

- if  $q \notin N_S(s) \cup N_O(o)$ , then  $o$  stays in its old cluster,
- if  $q \in N_O(o)$ , then  $q$  is assigned to  $o$ 's cluster,
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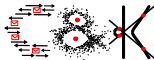
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- if  $q \in N_S(s) \setminus N_O(o)$  then  $q$  is assigned to the cluster belonging to  $s_{oq}$ .

## Observation

$$0 \leq \sum_{q \in N_O(o)} D(q, o) - D(q, s_q) + \sum_{q \in N_S(s) \setminus N_O(o)} D(q, s_{oq}) - D(q, s).$$



## Lemma 5.5

Let  $S$  be a stable set. Then

$$0 \leq D(P, O) - 3D(P, S) + 2R,$$

where  $R := \sum_{q \in P} D(q, s_{o_q})$ .



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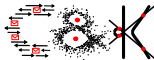
where  $R := \sum_{q \in P} D(q, s_{o_q})$ .

## Lemma 5.6

$$R \leq 4D(P, O) + (1 + 4/\alpha)D(P, S),$$

where

$$\alpha^2 := \frac{D(P, S)}{D(P, O)}.$$



## Lemma 5.7

Let  $\beta_1, \dots, \beta_n$  and  $\gamma_1, \dots, \gamma_n$  be two sequences of real numbers and set

$$\alpha^2 := \frac{\sum_{i=1}^n \gamma_i^2}{\sum_{i=1}^n \beta_i^2}.$$

Then

$$\sum_{i=1}^n \gamma_i \beta_i \leq \frac{1}{\alpha} \sum_{i=1}^n \gamma_i^2.$$