# Kapitel 5: Local Search

Inhalt:

- Gradient Descent (Hill Climbing)
- Metropolis Algorithm and Simulated Annealing
- Local Search in Hopfield Neural Networks
- Local Search for Max-Cut
  - Single-flip neighborhood
  - K-flip neighborhood
  - KL-neighborhood
- Nash Equilibria

## Finding a Nash Equilibrium

Theorem. The following algorithm terminates with a Nash equilibrium.

```
Best-Response-Dynamics(G, c) {
    Pick a path for each agent
    while (not a Nash equilibrium) {
        Pick an agent i who can improve by switching paths
        Switch path of agent i
    }
}
```

Pf. Consider a set of paths  $P_1, ..., P_k$ .

• Let  $x_e$  denote the number of paths that use edge e.

H(0) = 0, 
$$H(k) = \sum_{i=1}^{k} \frac{1}{i}$$

- Let  $\Phi(P_1, ..., P_k) = \Sigma_{e \in E} c_e \cdot H(x_e)$  be a potential function.
- Since there are only finitely many sets of paths, it suffices to show that  $\Phi$  strictly decreases in each step.

## Finding a Nash Equilibrium

- Pf. (continued)
- Consider agent j switching from path  $P_j$  to path  $P_j'$ .
- Agent j switches because



• 
$$\Phi$$
 increases by  $\sum_{f \in P_j' - P_j} c_f \left[ H(x_f + 1) - H(x_f) \right] = \sum_{f \in P_j' - P_j} \frac{c_f}{x_f + 1}$ 

- $\Phi$  decreases by  $\sum_{e \in P_j P_j'} c_e \left[ H(x_e) H(x_e 1) \right] = \sum_{e \in P_j P_j'} \frac{c_e}{x_e}$
- Thus, net change in  $\Phi$  is negative. •

#### Bounding the Price of Stability

Claim. Let  $C(P_1, ..., P_k)$  denote the total cost of selecting paths  $P_1, ..., P_k$ . For any set of paths  $P_1, ..., P_k$ , we have

 $C(P_1,...,P_k) \leq \Phi(P_1,...,P_k) \leq H(k) \cdot C(P_1,...,P_k)$ 

Pf. Let  $x_e$  denote the number of paths containing edge e.

• Let  $E^+$  denote set of edges that belong to at least one of the paths  $P_1, \ldots, P_k$ .

$$C(P_{1},...,P_{k}) = \sum_{e \in E^{+}} c_{e} \leq \sum_{e \in E^{+}} c_{e} H(x_{e}) \leq \sum_{e \in E^{+}} c_{e} H(k) = H(k) C(P_{1},...,P_{k})$$

### Bounding the Price of Stability

Theorem. There is a Nash equilibrium for which the total cost to all agents exceeds that of the social optimum by at most a factor of H(k).

Pf.

- Let  $(P_1^*, ..., P_k^*)$  denote set of socially optimal paths.
- Run best-response dynamics algorithm starting from P\*.
- Since  $\Phi$  is monotone decreasing  $\Phi(P_1, ..., P_k) \leq \Phi(P_1^*, ..., P_k^*)$ .

$$C(P_{1},...,P_{k}) \leq \Phi(P_{1},...,P_{k}) \leq \Phi(P_{1}^{*},...,P_{k}^{*}) \leq H(k) \cdot C(P_{1}^{*},...,P_{k}^{*})$$

$$\uparrow$$

$$previous claim$$

### Summary

Existence. Nash equilibria always exist for k-agent multicast routing with fair sharing.

Price of stability. Best Nash equilibrium is never more than a factor of H(k) worse than the social optimum.

Fundamental open problem.

(1) Find any Nash equilibria in poly-time.

(2) Find efficiently the Nash equilibria that achieve the bound H(k).

# Fragen?



# Kapitel 6: Randomized Algorithms

## Randomization

Algorithmic design patterns.

- Greedy.
- Divide-and-conquer.
- Dynamic programming.
- Approximation.
- Local Search.
- Randomization.

in practice, access to a pseudo-random number generator

Randomization. Allow fair coin flip in unit time.

Why randomize? Can lead to simplest, fastest, or only known algorithm for a particular problem.

Ex. Symmetry breaking protocols, graph algorithms, quicksort, hashing, load balancing, Monte Carlo integration, cryptography.

# Kapitel 6: Randomized Algorithms

Inhalt:

- Contention Resolution (symmetry-breaking)
- Global Minimum Cut (contraction algorithm)
- Random Variables and their Expectations
  - Guessing Cards
  - Coupon Collector
- Max 3-SAT

### Contention Resolution in a Distributed System

Contention resolution. Given n processes  $P_1, ..., P_n$ , each competing for access to a shared database. If two or more processes access the database simultaneously, all processes are locked out. Devise protocol to ensure all processes get through on a regular basis.

Restriction. Processes can't communicate.

Challenge. Need symmetry-breaking paradigm.



### Contention Resolution: Randomized Protocol

Protocol. Each process requests access to the database at time t with probability p = 1/n independently of the other processes.

Claim. Let S[i, t] = event that process i succeeds in accessing the database at time t. Then  $1/(e \cdot n) \leq \Pr[S(i, t)] \leq 1/(2n)$ .



Useful facts from calculus. As n increases from 2, the function:

- $(1 1/n)^n$  converges monotonically from 1/4 up to 1/e
- $(1 1/n)^{n-1}$  converges monotonically from 1/2 down to 1/e.

### Contention Resolution: Randomized Protocol

Claim. The probability that process i fails to access the database in en rounds is at most 1/e. After  $e \cdot n(c \ln n)$  rounds, the probability is at most  $n^{-c}$ .

Pf. Let F[i, t] = event that process i fails to access database in rounds 1 through t. By independence and previous claim, we have  $Pr[F(i, t)] \leq (1 - 1/(en))^{t}$ .

- Choose  $t = \lceil e \cdot n \rceil$ :  $\Pr[F(i,t)] \le \left(1 \frac{1}{en}\right)^{en} \le \left(1 \frac{1}{en}\right)^{en} \le \frac{1}{e}$
- Choose  $t = [e \cdot n] [c \ln n]$ :  $\Pr[F(i, t)] \leq \left(\frac{1}{e}\right)^{c \ln n} = n^{-c}$

#### Contention Resolution: Randomized Protocol

Claim. The probability that all processes succeed within  $2e \cdot n \ln n$  rounds is at least 1 - 1/n.

Pf. Let F[t] = event that at least one of the n processes fails to access database in any of the rounds 1 through t.



. Choosing t =  $\lceil en \rceil \lceil 2 \ln n \rceil$  yields  $\Pr[F[t]] \le n \cdot n^{-2} = 1/n$ .

Union bound. Given events 
$$E_1, ..., E_n$$
,  $\Pr\left[\bigcup_{i=1}^n E_i\right] \le \sum_{i=1}^n \Pr[E_i]$